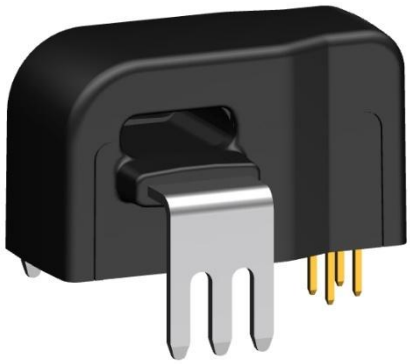
Current Sensor

Product Series： STK-PL/P1

Part number：
STK-10PL/P1
STK-20PL/P1
STK-32PL/P1
STK-40PL/P1
STK-50PL/P1

Version: Ver1.1



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CONTENT

1. Summary

The STK-PL/P1 series is based on TMR (Tunneling-Magnetoresistance) technology and open-loop design. It is suitable for DC, AC, pulsed and any kind of irregular current measurement under the isolated conditions. The nominal current range of the STK-PL current sensor consists of 10 A, 20 A, 32 A, 40 A, 50 A.

Typical applications

- PV combiner box
- PV inverter (MPPT & AC)
- motor driver controller
- SMPS & UPS
- Battery management system

Standards

- EN50178:1997
- IEC 61010-1:2010
- IEC 61326-1:2012

General parameter

Parameter	Symbol	Unit	Value
Working temperature	T_A	℃	-40 ~ 105
Storage temperature	T_stg	℃	-40 ~ 105
Mass	m	g	10

Absolute maximum rating

Parameter	Symbol	Unit	Value
Supply voltage（non-destructive）	V_C	V	6.0
ESD rating（HBM）	U_{ESD}	kV	4
ESD rating（CDM）	U_{CDM}	kV	1.5

Remark: the unrecoverable damage may occur when the product works on the conditions over the absolute maximum ratings. Long-time working on the absolute maximum ratings may cause the degradation on performance and reliability.

Ratings

Parameter	Symbol	Unit	Value
Ambient operating temperature	T_A	℃	105
Primary current	I_p	A	According to series primary current
Secondary supply voltage	U_c	V DC	5

Isolation parameter

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC test 50Hz/1 min	Ud	kV	5	
Impulse withstand voltage 1.2/50μs	Ûw	kV	8	
Clearance distance (pri. -sec)	dCl	mm	8	Shortest distance through air
Creepage distance (pri. -sec)	dCp	mm	8	Shortest path along device body
Case material			V0 according to UL 94	
Application example		V	600	Reinforced insulation, CAT III, PD 2, non uniform field according EN 50178, IEC 61010
Application example		V	1000	Basic insulation, CAT III, PD 2, non uniform field according EN 50178, IEC 61010
Application example		V	1500	Basic insulation, CAT III, PD 2, according to IEC 62109-1 Altitude ≤ 3000 m
Application example		V	600	CAT III, PD 2, according to UL 508

2. STK-10PL/P1 Electrical performance

Condition：T_A = 25℃ Vcc =3.3 V (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I_pn	A		10		
Primary current measuring range	I_pm	A	-30		30	
Supply voltage	Vcc	V	3.135	3.3	3.465	
Current consumption	Icc	mA		5	10	
Reference voltage	Vref	V	1.63	1.65	1.67	Output function
Rated output voltage`	V_FS	V		0.46		Vout - Vref @ I_pn
Internal output resistance	R_out	Ω		1		Vout @ 0 A
Internal output resistance	R_ref	Ω		1		Vref@ 0 A
Quiescent voltage	Voff	V	1.63	1.65	1.67	Vout @ 0 A
Electrical offset voltage	Voe	mV	-10		10	(Vout – Vref) @ 0 A
Temperature drift of Voe	Voe_TRange	mV	-6.9		6.9	-40℃ ~ 105℃
Magnetic offset current	I_om	A	-0.25		0.25	@ ±10 x I_pn
Theoretical gain	G_th	mV/A		46		460 mV @ I_pn
Error of gain	Err_G	%G_th	-0.5		0.5	Trimmed in the factory @ 25℃
Temperature drift of gain	Err_G_TRange	%V_FS	-1.0		1.0	-40℃ ~ 105℃
Rated linearity error	Non-L	%I_pn	-0.5		0.5	±I_pn
Linearity error @ I_pm	Non-L	%I_pm	-3		3	±I_pm
Reaction time	t_ra	μs		0.5		@10% of I_pn
Step response time	t_res	μs		1.5		@90% of I_pn
Delay time	t_delay	μs		1		400 kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		400		No RC circuit
Output voltage noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		 15 25		
Accuracy @ 25℃	X	% of I_pn	-1		1	@ 25℃
Accuracy @ -40℃ ~ 105℃	X_TRange	% of I_pn	-2		2	-40℃ ~ 105℃

3. STK-20PL/P1 Electrical performance

Condition：T_A = 25℃ Vcc = 3.3 V (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I_pn	A		20		
Primary current measuring range	I_pm	A	-60		60	
Supply voltage	Vcc	V	3.135	3.3	3.465	
Current consumption	Icc	mA		5	10	
Reference voltage	Vref	V	1.63	1.65	1.67	Output function
Rated output voltage`	V_FS	V		0.46		Vout - Vref @ I_pn
Internal output resistance	R_out	Ω		1		Vout @ 0 A
Internal output resistance	R_ref	Ω		1		Vref@ 0 A
Quiescent voltage	Voff	V	1.63	1.65	1.67	Vout @ 0 A
Electrical offset voltage	Voe	mV	-10		10	(Vout – Vref) @ 0 A
Temperature drift of Voe	Voe_TRange	mV	-6.9		6.9	-40℃ ~ 105℃
Magnetic offset current	I_om	A	-0.25		0.25	@ ±10 x I_pn
Theoretical gain	G_th	mV/A		23		460 mV @ I_pn
Error of gain	Err_G	%G_th	-0.5		0.5	Trimmed in the factory @ 25℃
Temperature drift of gain	Err_G_TRange	%V_FS	-1.0		1.0	-40℃ ~ 105℃
Rated linearity error	Non-L	%I_pn	-0.5		0.5	±I_pn
Linearity error @ I_pm	Non-L	%I_pm	-3		3	±I_pm
Reaction time	t_ra	μs		0.5		@10% of I_pn
Step response time	t_res	μs		1.5		@90% of I_pn
Delay time	t_delay	μs		1		400 kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		400		No RC circuit
Output voltage noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		 12 17		
Accuracy @ 25℃	X	% of I_pn	-1		1	@ 25℃
Accuracy @ -40 ℃ ~ 105℃	X_TRange	% of I_pn	-2		2	-40℃ ~ 105℃

4. STK-32PL/P1 Electrical performance

Condition：T_A = 25℃ Vcc =3.3 V (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I_pn	A		32		
Primary current measuring range	I_pm	A	-96		96	
Supply voltage	Vcc	V	3.135	3.3	3.465	
Current consumption	Icc	mA		5	10	
Reference voltage	Vref	V	1.63	1.65	1.67	Output function
Rated output voltage`	V_FS	V		0.46		Vout - Vref @ I_pn
Internal output resistance	R_out	Ω		1		Vout @ 0 A
Internal output resistance	R_ref	Ω		1		Vref@ 0 A
Quiescent voltage	Voff	V	1.63	1.65	1.67	Vout @ 0 A
Electrical offset voltage	Voe	mV	-10		10	(Vout – Vref) @ 0 A
Temperature drift of Voe	Voe_TRange	mV	-6.9		6.9	-40℃ ~ 105℃
Magnetic offset current	I_om	A	-0.25		0.25	@ ±10 x I_pn
Theoretical gain	G_th	mV/A		14.4		460 mV @ I_pn
Error of gain	Err_G	%G_th	-0.5		0.5	Trimmed in the factory @ 25℃
Temperature drift of gain	Err_G_TRange	%V_FS	-1.0		1.0	-40℃ ~ 105℃
Rated linearity error	Non-L	%I_pn	-0.5		0.5	±I_pn
Linearity error @ I_pm	Non-L	%I_pm	-3		3	±I_pm
Reaction time	t_ra	μs		0.5		@10% of I_pn
Step response time	t_res	μs		1.5		@90% of I_pn
Delay time	t_delay	μs		1		400 kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		400		No RC circuit
Output voltage noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		 12 17		
Accuracy @ 25℃	X	% of I_pn	-1		1	@ 25℃
Accuracy @ -40℃ ~ 105℃	X_TRange	% of I_pn	-2		2	-40℃ ~ 105℃

5. STK-40PL/P1 Electrical performance

Condition：T_A = 25℃ Vcc =3.3 V (Except special instructions)

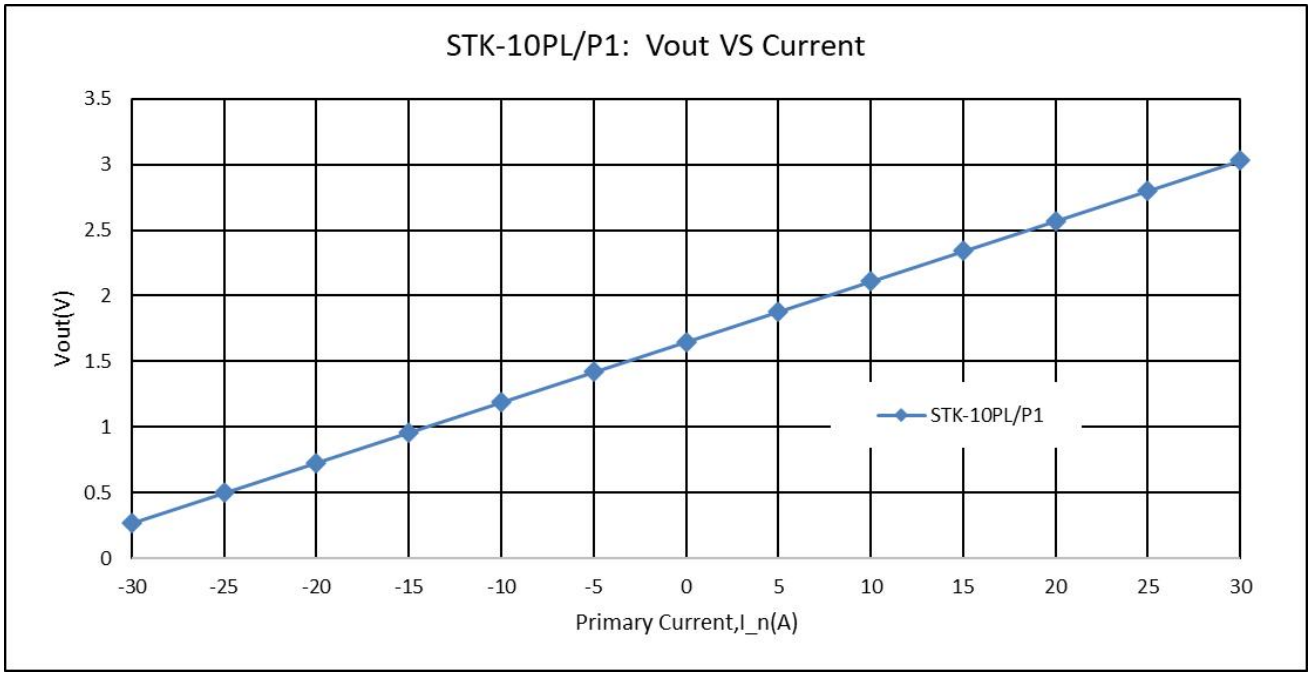
Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I_pn	A		40		
Primary current measuring range	I_pm	A	-120		120	
Supply voltage	Vcc	V	3.135	3.3	3.465	
Current consumption	Icc	mA		5	10	
Reference voltage	Vref	V	1.63	1.65	1.67	Output function
Rated output voltage`	V_FS	V		0.46		Vout - Vref @ I_pn
Internal output resistance	R_out	Ω		1		Vout @ 0 A
Internal output resistance	R_ref	Ω		1		Vref @ 0 A
Quiescent voltage	Voff	V	1.63	1.65	1.67	Vout @ 0 A
Electrical offset voltage	Voe	mV	-10		10	(Vout – Vref) @ 0 A
Temperature drift of Voe	Voe_TRange	mV	-6.9		6.9	-40℃ ~ 105℃
Magnetic offset current	I_om	A	-0.25		0.25	@ ±10 x I_pn
Theoretical gain	G_th	mV/A		11.5		460 mV @ I_pn
Error of gain	Err_G	%G_th	-0.5		0.5	Trimmed in the factory @ 25℃
Temperature drift of gain	Err_G_TRange	%V_FS	-1.0		1.0	-40℃ ~ 105℃
Rated linearity error	Non-L	%I_pn	-0.5		0.5	±I_pn
Linearity error @ I_pm	Non-L	%I_pm	-3		3	±I_pm
Reaction time	t_ra	μs		0.5		@10% of I_pn
Step response time	t_res	μs		1.5		@90% of I_pn
Delay time	t_delay	μs		1		400 kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		400		No RC circuit
Output voltage noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		 10 15		
Accuracy @ 25℃	X	% of I_pn	-1		1	@ 25℃
Accuracy @ -40℃ ~ 105℃	X_TRange	% of I_pn	-2		2	-40℃ ~ 105℃

6. STK-50PL/P1 Electrical performance

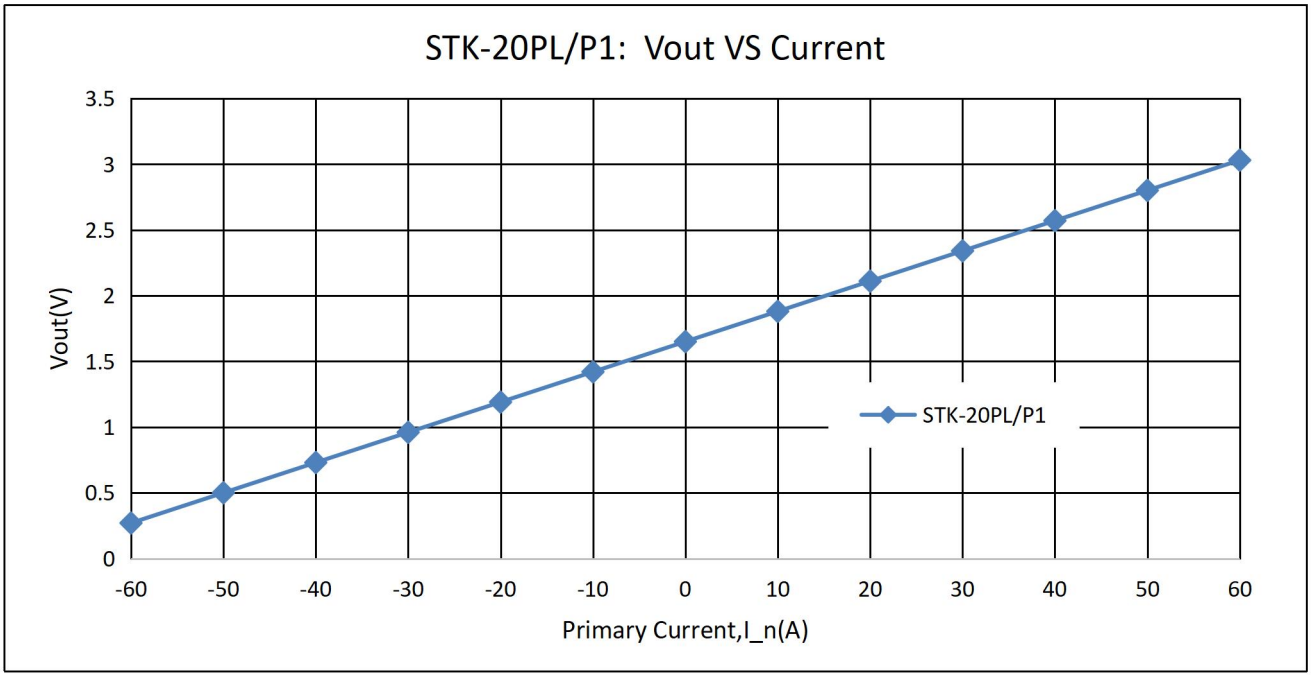
Condition：T_A = 25℃ Vcc = 3.3 V (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I_pn	A		50		
Primary current measuring range	I_pm	A	-150		150	
Supply voltage	Vcc	V	3.135	3.3	3.465	
Current consumption	Icc	mA		5	10	
Reference voltage	Vref	V	1.63	1.65	1.67	Output function
Rated output voltage`	V_FS	V		0.46		Vout - Vref @ I_pn
Internal output resistance	R_out	Ω		1		Vout @ 0 A
Internal output resistance	R_ref	Ω		1		Vref @ 0 A
Quiescent voltage	Voff	V	1.63	1.65	1.67	Vout @ 0 A
Electrical offset voltage	Voe	mV	-10		10	(Vout – Vref) @ 0 A
Temperature drift of Voe	Voe_TRange	mV	-6.9		6.9	-40℃ ~ 105℃
Magnetic offset current	I_om	A	-0.25		0.25	@ ±10 x I_pn
Theoretical gain	G_th	mV/A		9.2		460 mV @ I_pn
Error of gain	Err_G	%G_th	-0.5		0.5	Trimmed in the factory @ 25℃
Temperature drift of gain	Err_G_TRange	%V_FS	-1.0		1.0	-40℃ ~ 105℃
Rated linearity error	Non-L	%I_pn	-0.5		0.5	±I_pn
Linearity error @ I_pm	Non-L	%I_pm	-3		3	±I_pm
Reaction time	t_ra	μs		0.5		@10% of I_pn
Step response time	t_res	μs		1.5		@90% of I_pn
Delay time	t_delay	μs		1		400 kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		400		No RC circuit
Output voltage noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		 10 15		
Accuracy @ 25℃	X	% of I_pn	-1		1	@ 25℃
Accuracy @ -40℃ ~ 105℃	X_TRange	% of I_pn	-2		2	-40℃ ~ 105℃

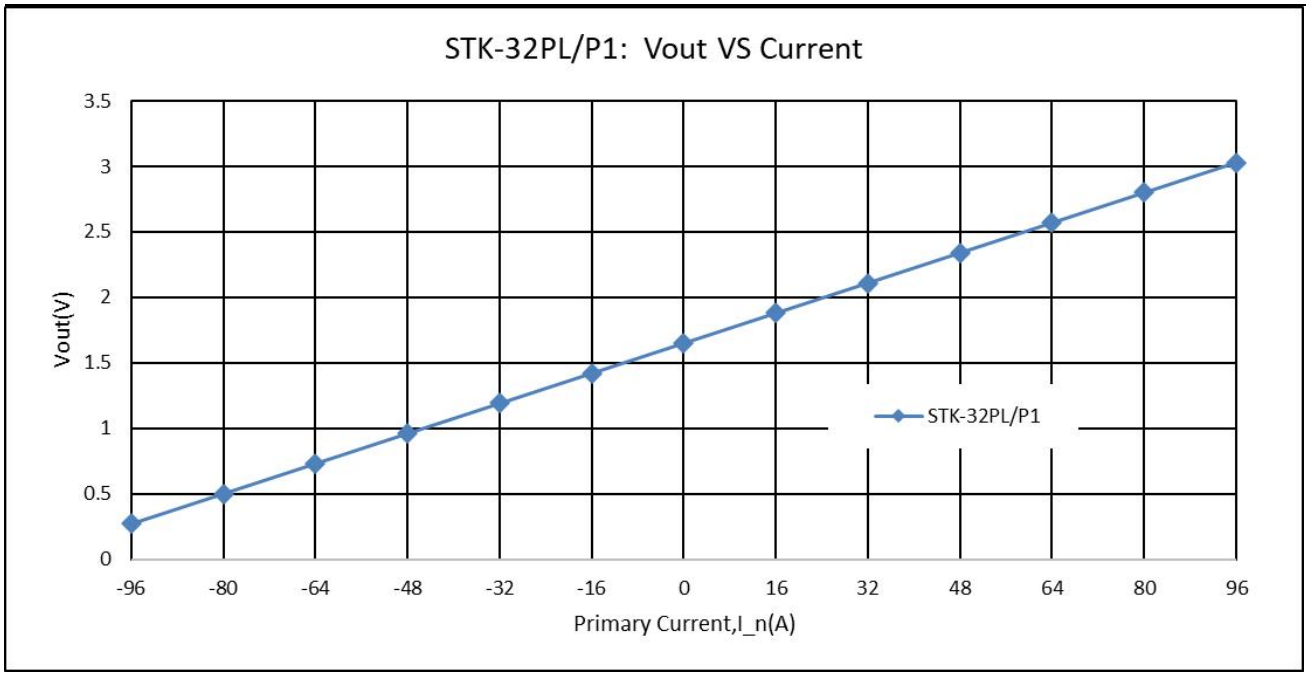
7. Output voltage VS primary current



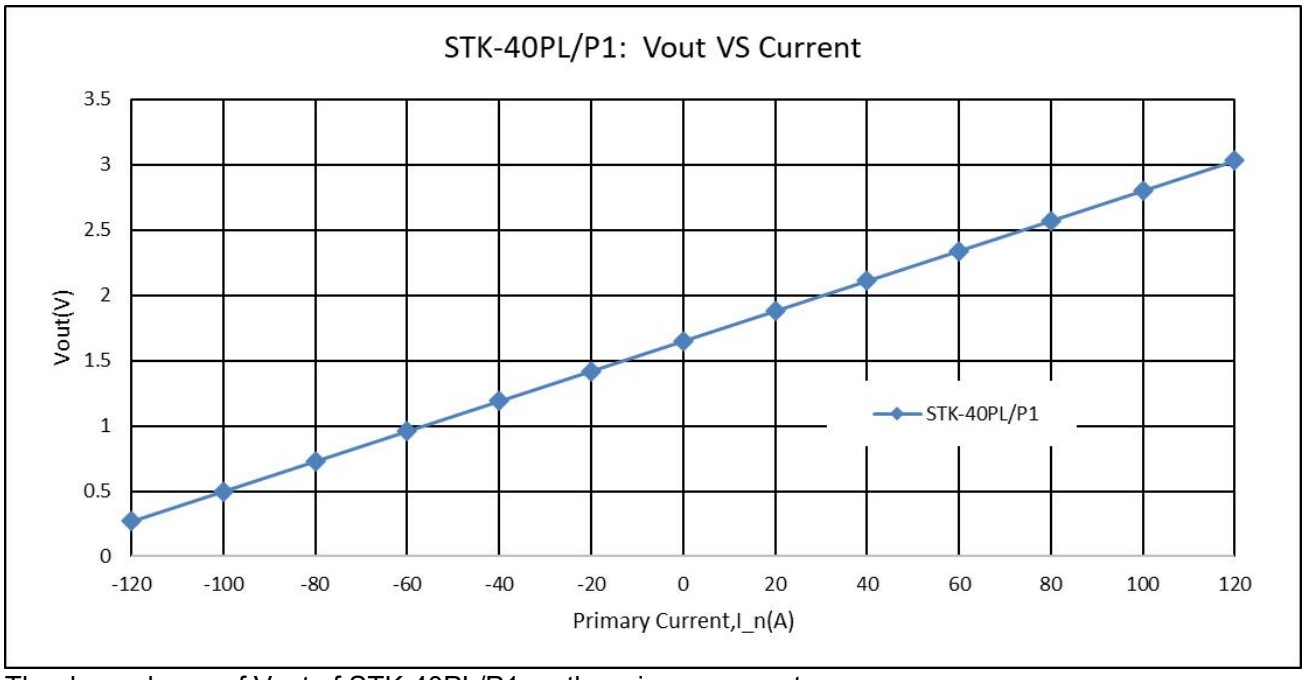
The dependence of Vout of STK-10PL/P1 on the primary current.



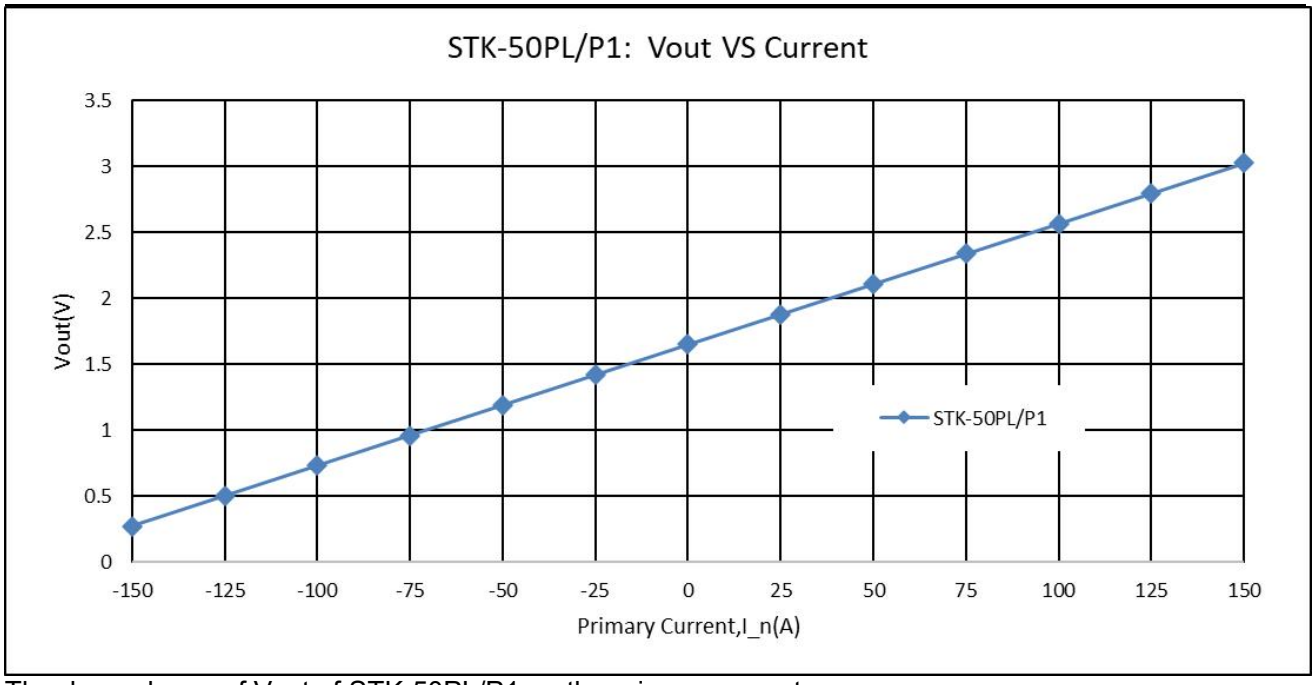
The dependence of Vout of STK-20PL/P1 on the primary current.



The dependence of Vout of STK-32PL/P1 on the primary current.

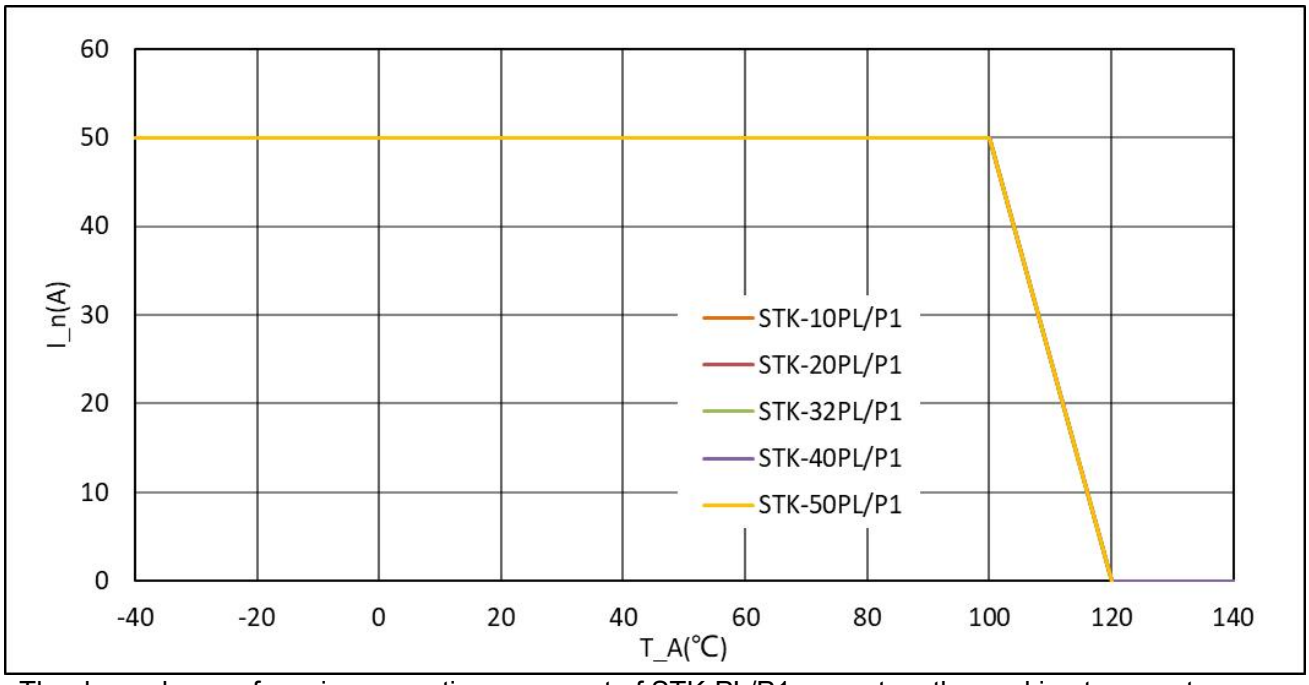


The dependence of Vout of STK-40PL/P1 on the primary current.



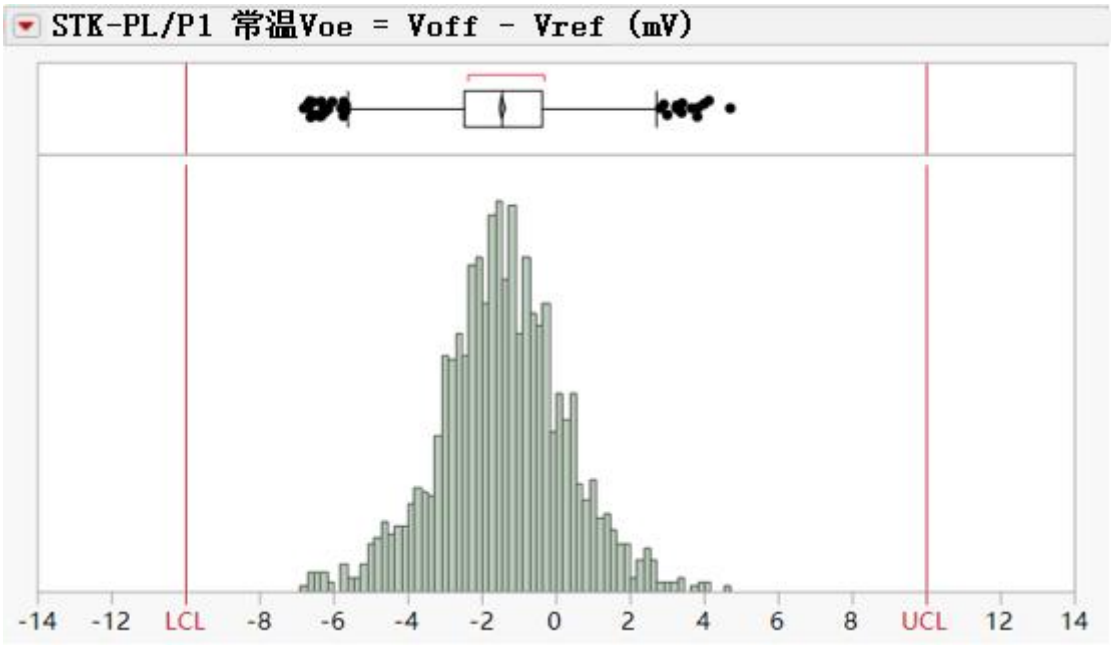
The dependence of Vout of STK-50PL/P1 on the primary current.

8. Maximum continues DC current

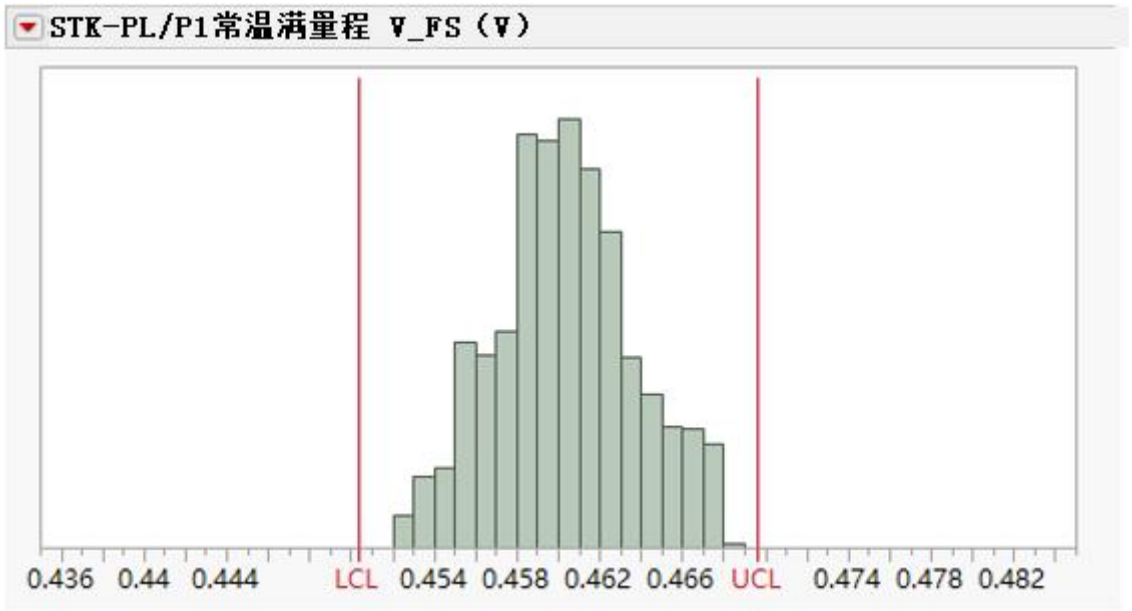


The dependence of maximum continues current of STK-PL/P1 current on the working temperature

9. Accuracy characteristics in room temperature

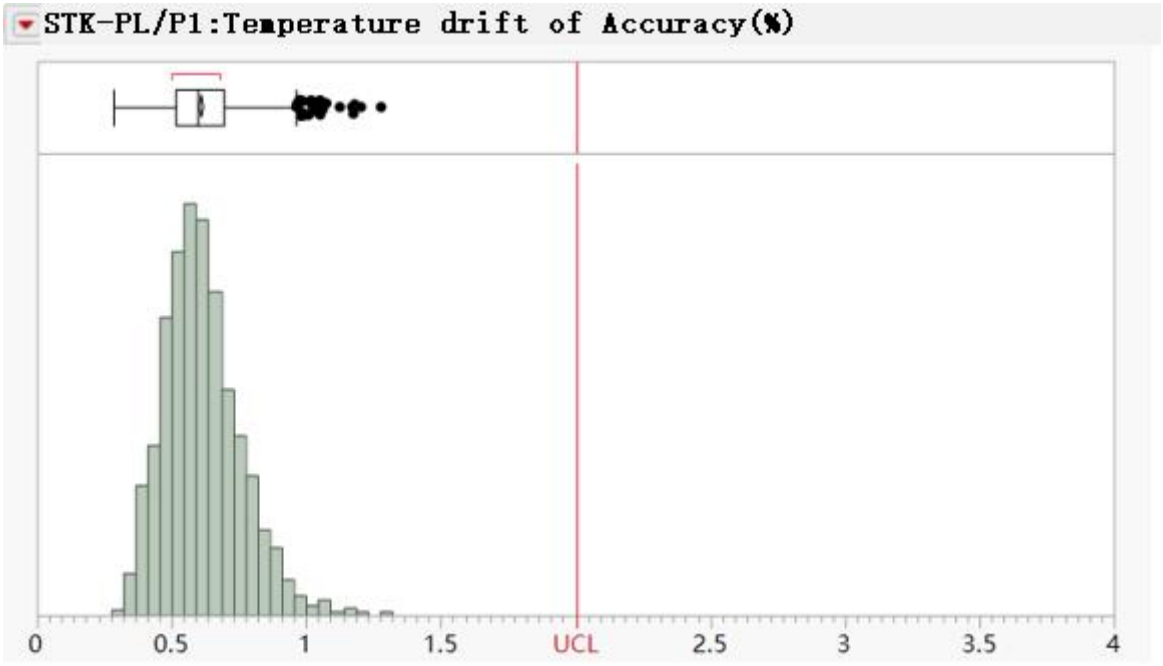


The distribution Voe of STK-PL/P1 current sensor at 25℃.

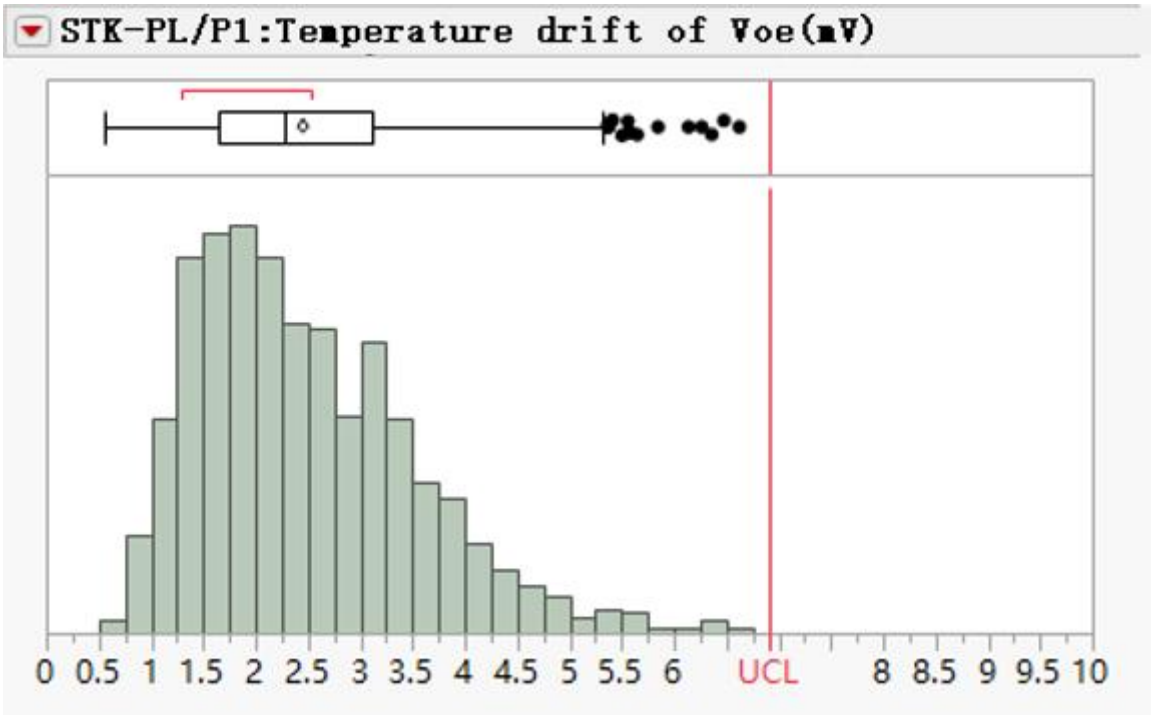


The distribution of V_FS OF STK-PL/P1 current sensor at 25℃.

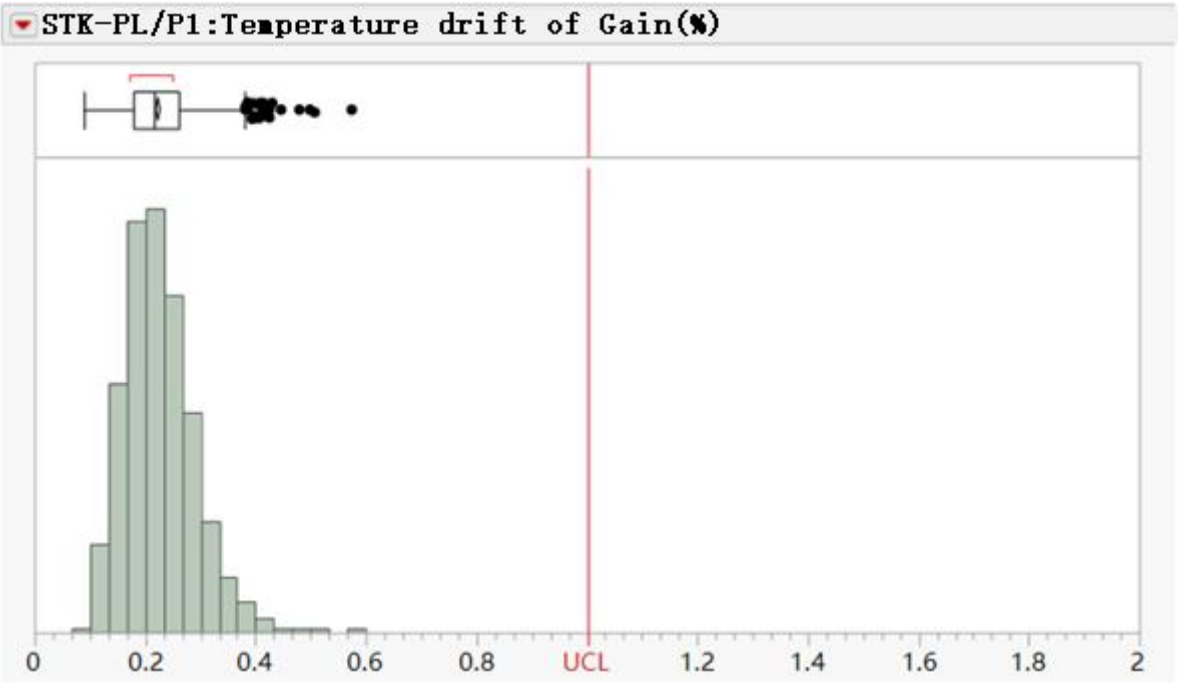
10. Accuracy cross temperature



The distribution of temperature drift of accuracy, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.



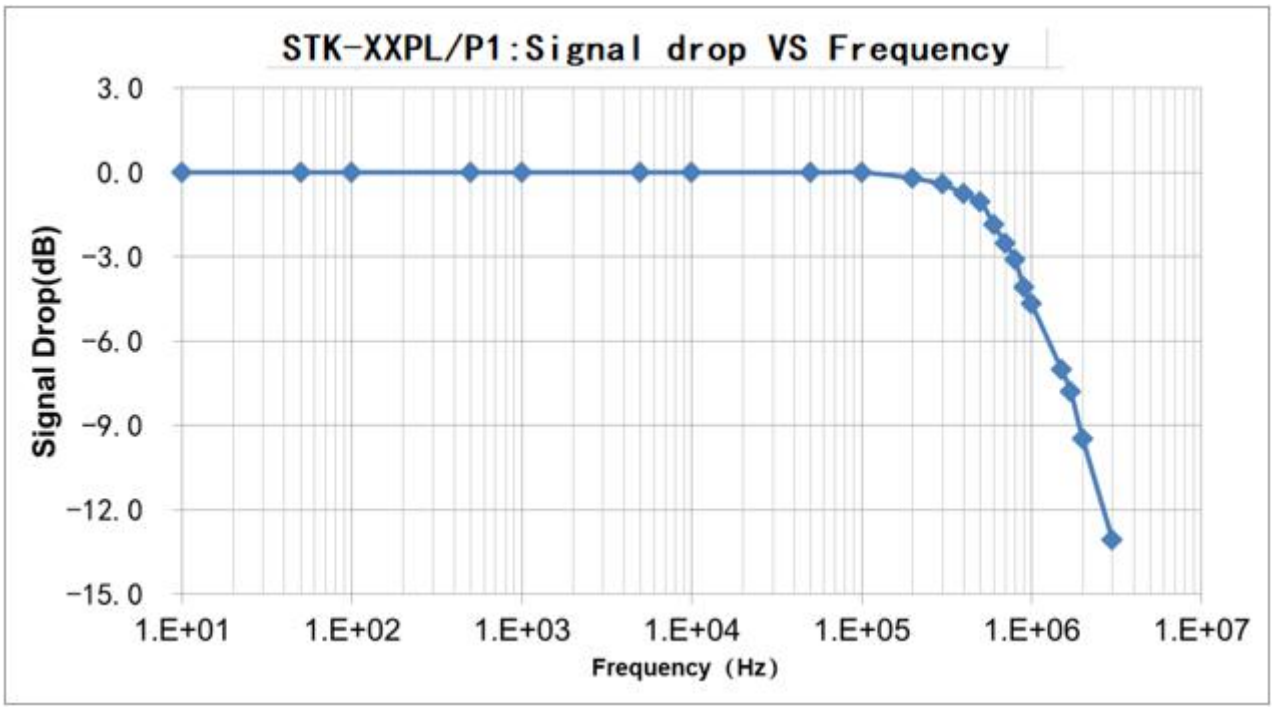
The distribution of temperature drift of Voe, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.



The distribution of temperature drift of GAIN, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.

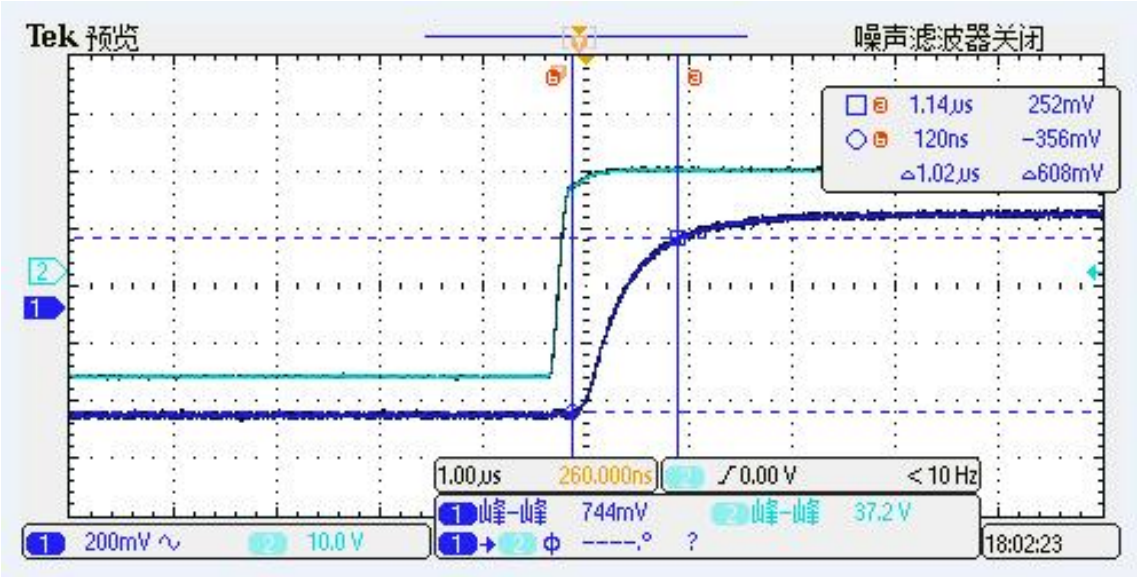
ed current.

11. Frequency response and bandwidth



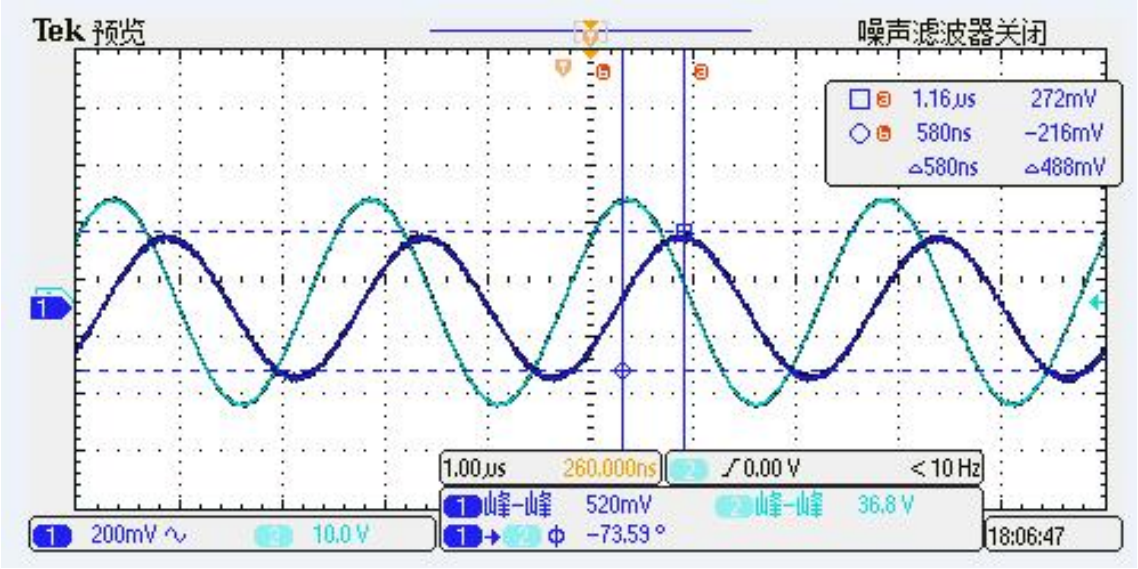
The frequency bandwidth of STK-PL/P1 series current sensor. The bandwidth of current sensor is DC ~ 400 kHz (-3dB).

12. Step response time



The typical frequency response of STK-xxPL/P1 current sensor. The response time from 90% of the primary current (light blue) to 90% of the secondary output (dark blue) is less than 1.5 μs

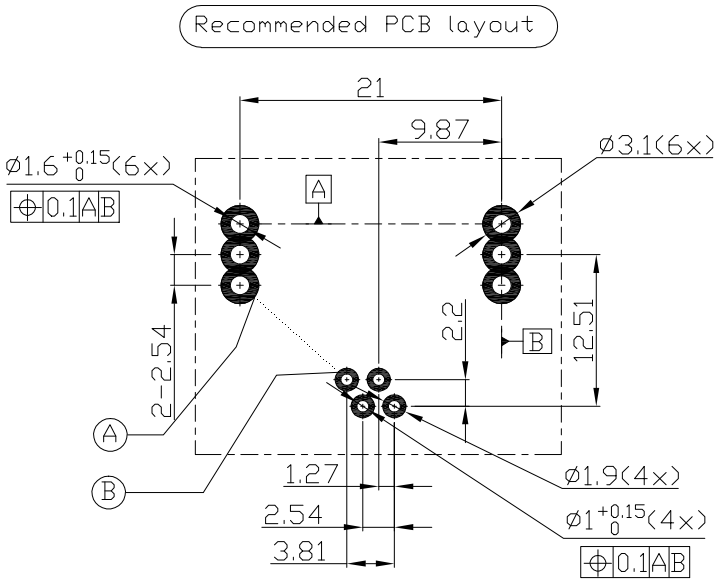
13. Frequency delay performance



When testing 400 kHz sine wave, the typical result of STK-xxPL/P1 current sensor's output. The response time from the primary current (light blue) to the secondary output (dark blue) is less than 1 μs.

14. Recommended PCB layout

Installation of view: overlooking (unit: mm)



	d_{CI}(mm)	d_{CP}(mm)
A-B	9.42	9.42

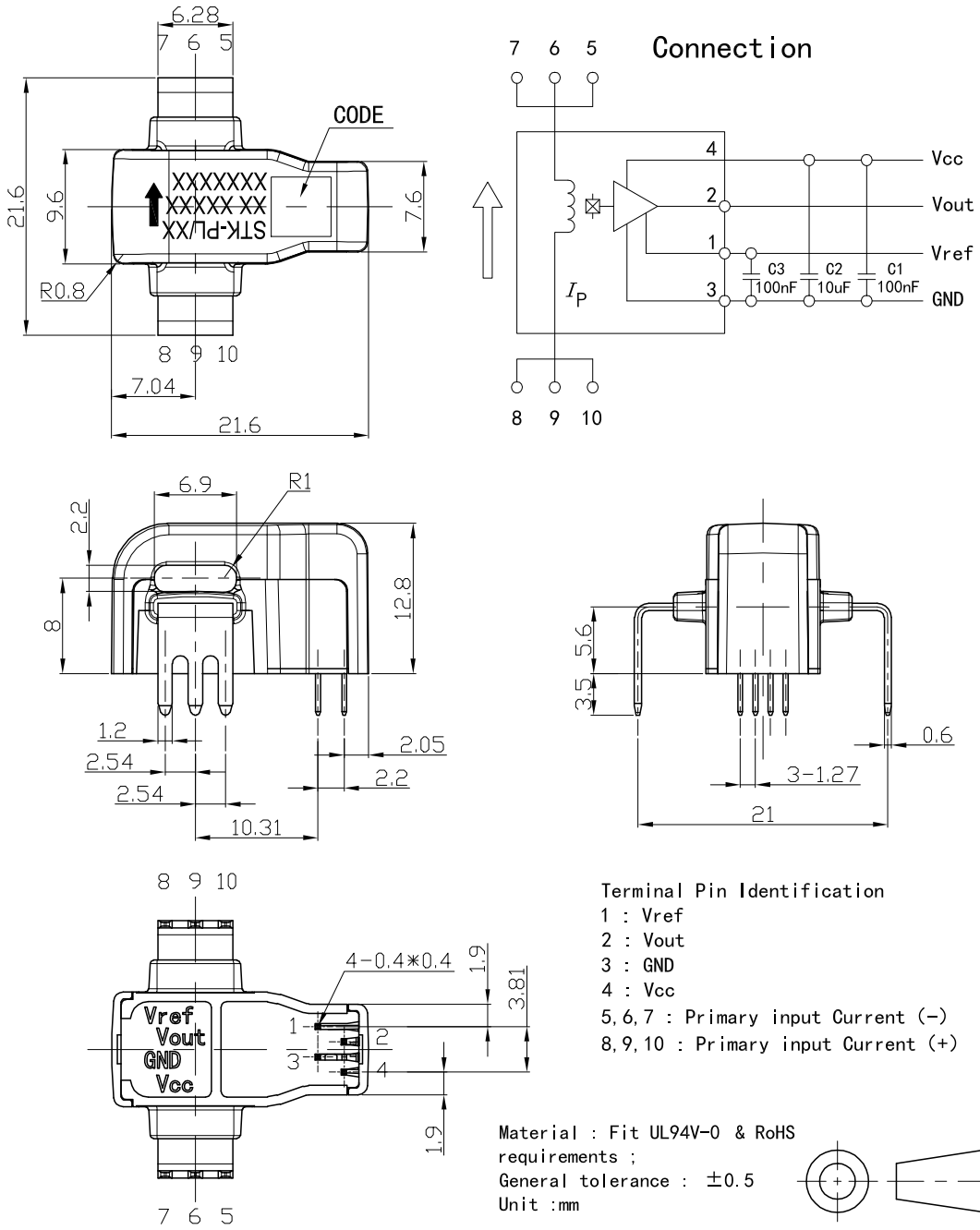
1. Installing angle：Overlook (observe from the side of installing transducer)
2. Recommended bore diameter of primary current line, (diameter of primary current × 1.2) mm
3. Recommended bore diameter of secondary current line, (diameter of secondary current × 1.2) mm
4. The maximum thickness of PCB is 2.5 mm
5. The curve of wave soldering: 260℃ × 10 s

Security：

This current sensor must be used in limited-energy secondary circuit according to IEC 61010-1.

- This current sensor must be used in electric/electronic equipment with respect to appliance standards and safety requirement in accordance with the manufacture's operating instructions;
- When operating the current sensor, certain parts of the module can carry hazardous voltage;
- Failure to wiring as shown in the diagram will damage the current sensor;
- Ignoring this warning can lead to serious consequences.
- A protective housing or a additional shield could be used.
- Main supply must be able to disconnected.

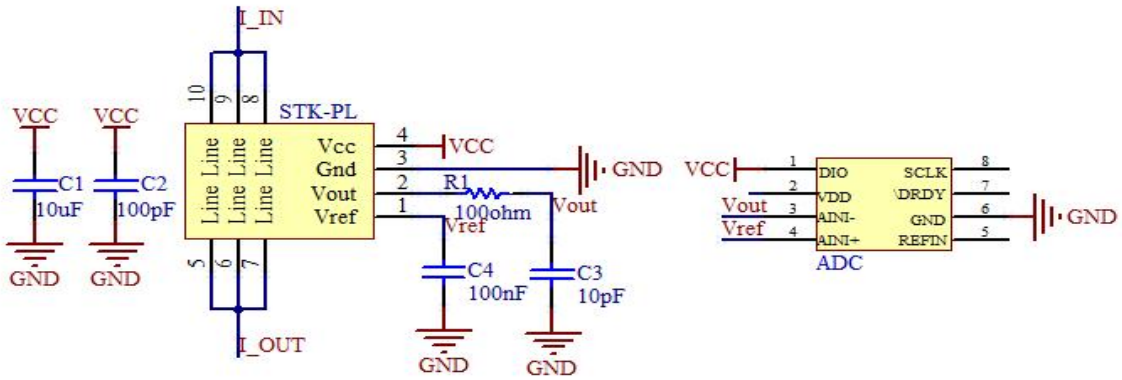
15. Dimension & Pin definitions

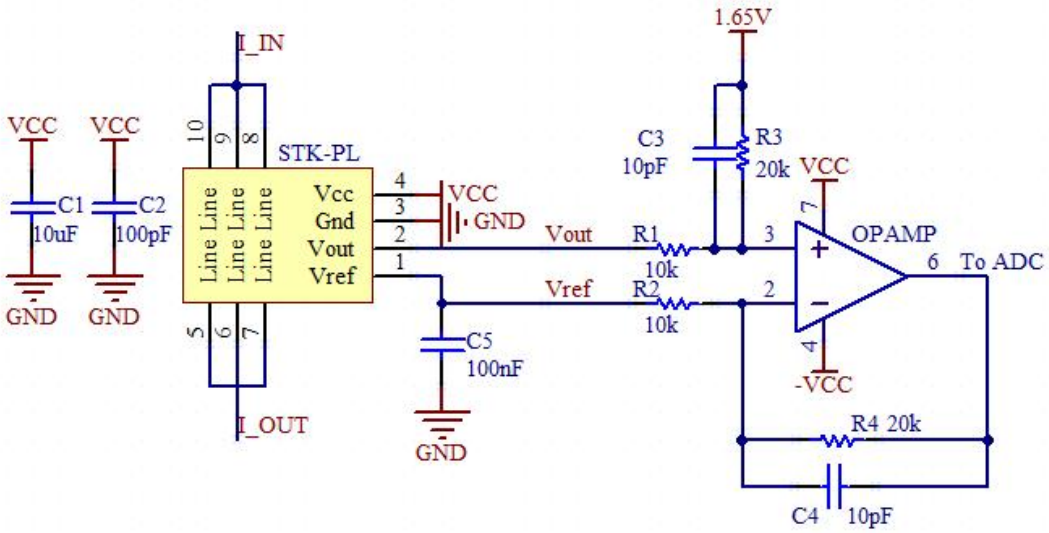


Terminal Pin Identification
1 : Vref
2 : Vout
3 : GND
4 : Vcc
5, 6, 7 : Primary input Current (-)
8, 9, 10 : Primary input Current (+)

Material : Fit UL94V-0 & RoHS requirements ;
General tolerance : ±0.5
Unit :mm

16. Appendix: typical application circuit





R3 (kohm)	C3 (pF)	Theoretical -3dB f = 1/(2πRC) (kHz)	Measured -3dB (kHz)
20	20	398	~ 400
20	81	98	~ 100
20	810	10	~ 10

The frequency characteristics of STK_PL/P1 series current sensor are not affected by the R-C setting (according to recommended R-C setting), therefore the active filter circuit or R-C circuit can be applied to modulate the sensor's frequency characteristics.

The signal input to ADC is 1.65+ R4/R2*(Vout-Vref) with the conditions: R1 = R2, R3 = R4, C3 = C4.